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Analysis and Control" (Asada and Slotine, Wiley, 1986), and

"Applied Nonlinear Control"

(Slotine and Li, Prentice-Hall,

1991) and is one of the most cited researcher in both systems

science and robotics. He was a member of the French

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Textbook reference for lectures
1-13 is . Applied Nonlinear
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W., and Slotine, J.J.E., "On
Contraction Analysis for Nonlinear
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Sepulchre et al. - Springer, 1997

More focused on passivity and
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control systems - A. Isidori -
Springer Verlag, 1995 A reference
for geometric approach Applied
Nonlinear control - J.J. Slotine and
W. Li - Prentice-Hall, 1991 An
interesting reference in particular
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Control of Nonlinear Systems
People The Nonlinear Systems
Laboratory is headed by Professor
Jean-Jacques Slotine. Members
and affiliates are Gabriel
Bousquet (g_b@mit.edu) Soon-Jo
Chung (sjchung@mit.edu) Joanna
Cohen (joannac@mit.edu) Khalid

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El-Rifai (elrifai@mit.edu) Winfried
Lohmiller
(wslohmil@mit.edu) Quang-Cuong
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Scientific, 2004, (ISBN
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to help students understand a
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systems, because all real control
systems are nonlinear. These
systems are often governed by

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nonlinear differential equations.

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